

20th **UITIC**
INTERNATIONAL TECHNICAL
FOOTWEAR CONGRESS

Porto
2018
16th–18th
MAY

FROM FASHION TO FACTORY

A New Technological Age



**“Virtual fitting room based
on augmented reality”**

Dr. Javier Cortés Cameros. Project Management Office



FOOTWEAR TECHNOLOGY CENTER OF LA RIOJA

“Virtual fitting room based on augmented reality”



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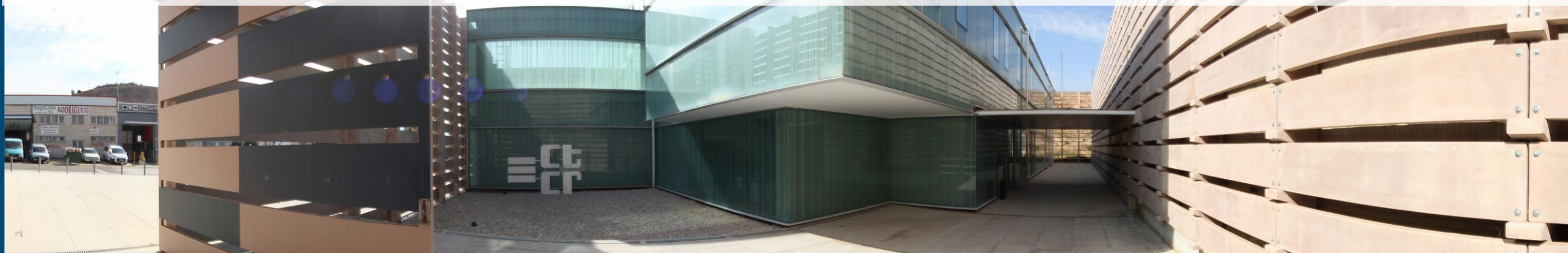
MISSION Innovation for the future
Private non-profit association

- I+D+i to create added value
- Improvement of the industrial competitiveness
- Certification of quality
- Over 10 years of experience offering technological solutions



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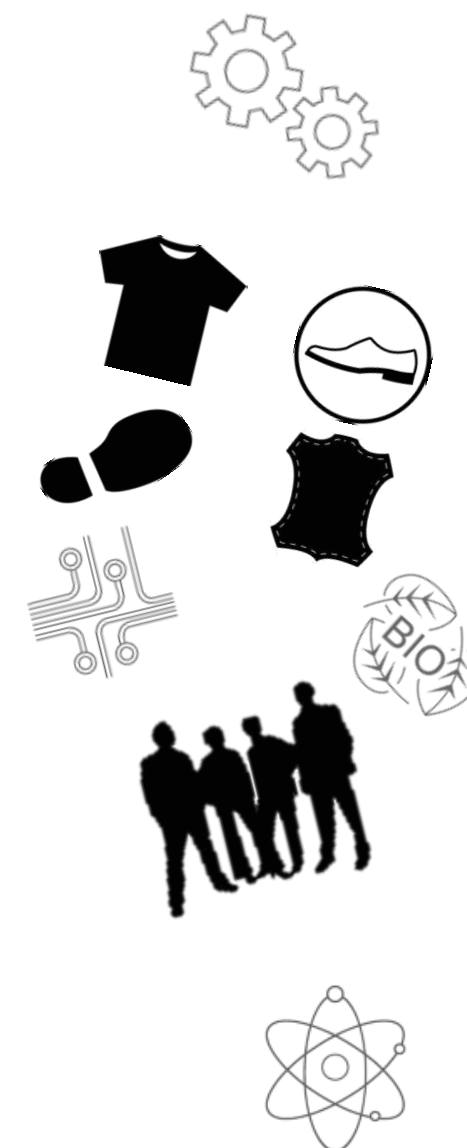
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FACTS & FIGURES

- ≡ **+ 110 associated companies**, 80 % of them are footwear manufacturers or distributors.
- ≡ **+ 170 clients** have contracted **390 specialized** services.
- ≡ The team of **CTCR** is composed of **24 people**.
- ≡ Around **28-30 projects per year**, with an average budget of **1.3 million €**.
- ≡ Over **4,000 workers** have participated in more than **5,673 hours** of training.



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KNOW-HOW



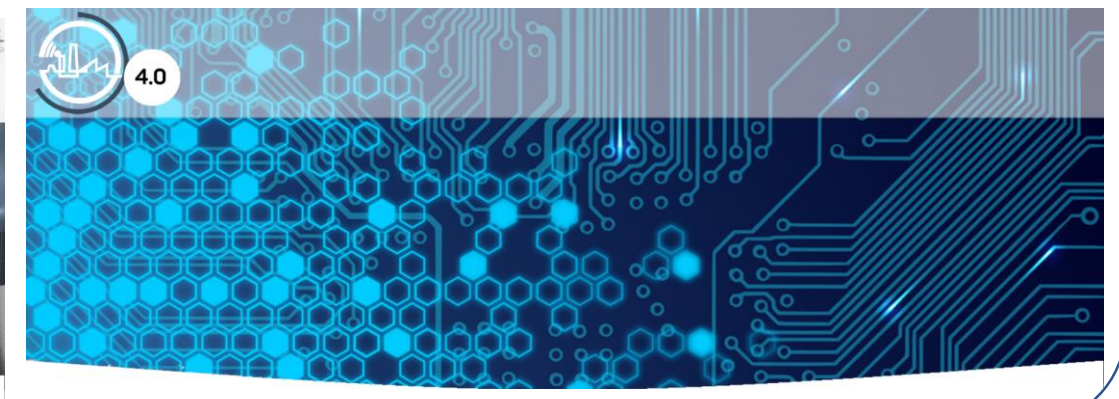
ICT



Mechanics & Prototyping



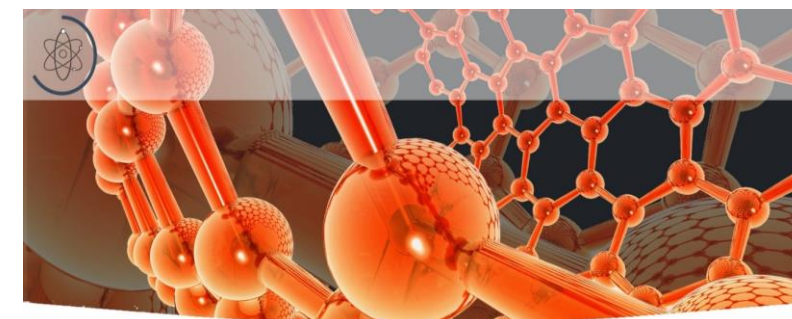
Electronics & Automation



Environment & Biotechnology



Nanotechnology & New Materials

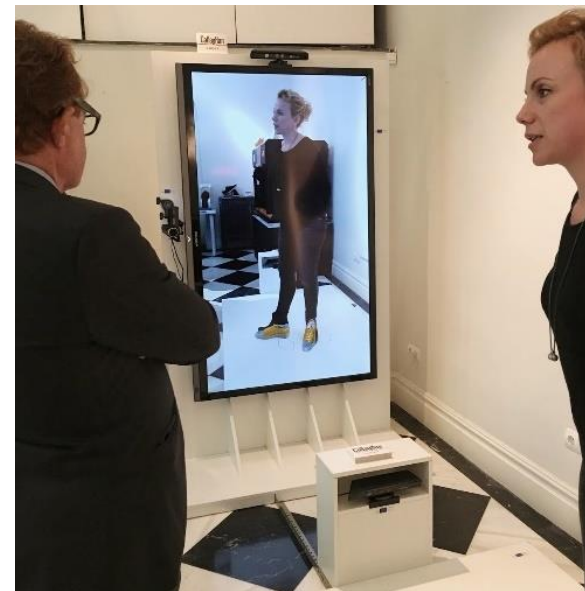


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OBJECTIVES

- ≡ New algorithm for the **compression and decompression of images** in real time
- ≡ **Augmented reality** created through images and 3D models.
- ≡ **Kinesthetic virtual fitting room** that can work in real time.
- ≡ **Positioning and movement** of the virtual shoe:
 1. Show the suitable picture of the shoe.
 2. Vector precision $\pm 2^\circ$.
 3. 16,380 pictures per model.
 4. Combination of models and colours in real time.

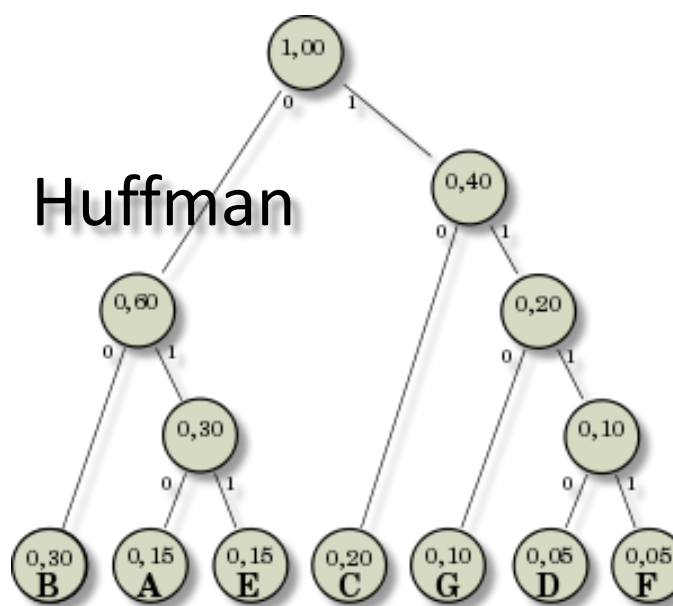


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STATE OF THE ART

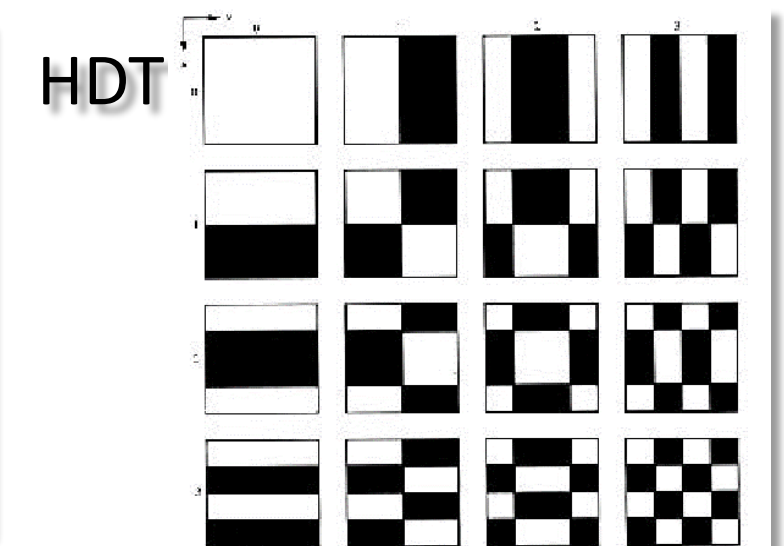
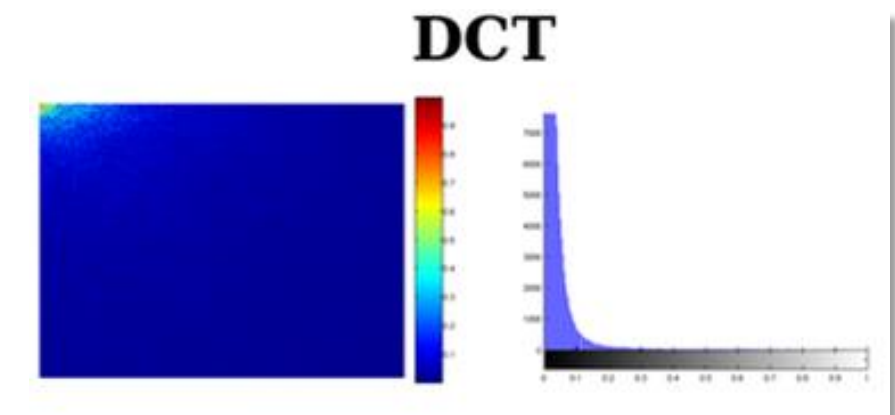
Study of the Art was focused on compression algorithms currently used to compress and decompress images:

- ≡ Lossless Algorithm Lempel-Ziv
- ≡ Discrete Bi-dimensional Cosine Transform
- ≡ Discrete Hadamard Transform
- ≡ Huffman Algorithm.



Step	Input	String+char	In Table?	Temporary	Add To Table	Output
1	S	S		S	-	
2	H	SH	N	H	256 = SH	S
3	A	HA	N	A	257 = HA	H
4	I	AI	N	I	258 = AI	A
5	S	IS	N	S	259 = IS	I
6	H	SH	Y(256)	SH		
7	A	SHA	N	A	260 = SHA	256 ?
8	M	AM	N	M	261 = AM	A
9	S	MS	N	S	262 = MS	M
10	H	SH	Y(256)	SH		
11	A	SHA	Y(260)	SHA		
12	I	SHAI				
13	H					
14	A					
15	I					
16						

LZW



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SYSTEM REQUIREMENTS

ID	Name	Description
1	Image and prediction algorithms	<ul style="list-style-type: none">Algorithms to compress images to enable the work with pictures in real time.Algorithms to analyse which are the most probable images to be displayed and prepare them.Technology to manage the data volume: 16,380 images with 1,600x1,600 pixels
2	User interface	<ul style="list-style-type: none">Easy use and accessibility. Validation with final users.
3	Pose system	<ul style="list-style-type: none">Developments to understand the position of the foot and transform it in a mathematic expression.Developments for the augmented reality system.
4	Catalogue system	<ul style="list-style-type: none">Preparation of models and database.
5	Manufacturing of the virtual fitting room	<ul style="list-style-type: none">Structure and hardware
6	Marketing and sales	<ul style="list-style-type: none">User experience

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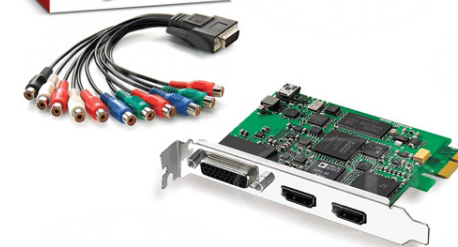
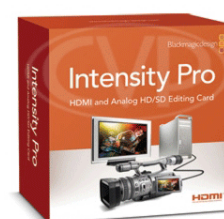
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DESIGN AND MANUFACTURING OF THE PROTOTYPE

Active components:

- Videocamera.
- TV screen.
- Kinect sensors.
- Frame structure.
- Specifically designed computer.



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INTERFACE

Best interfaces are based on the dynamic interpretation of movements and the displacement of graphic elements on display as options of a menu.

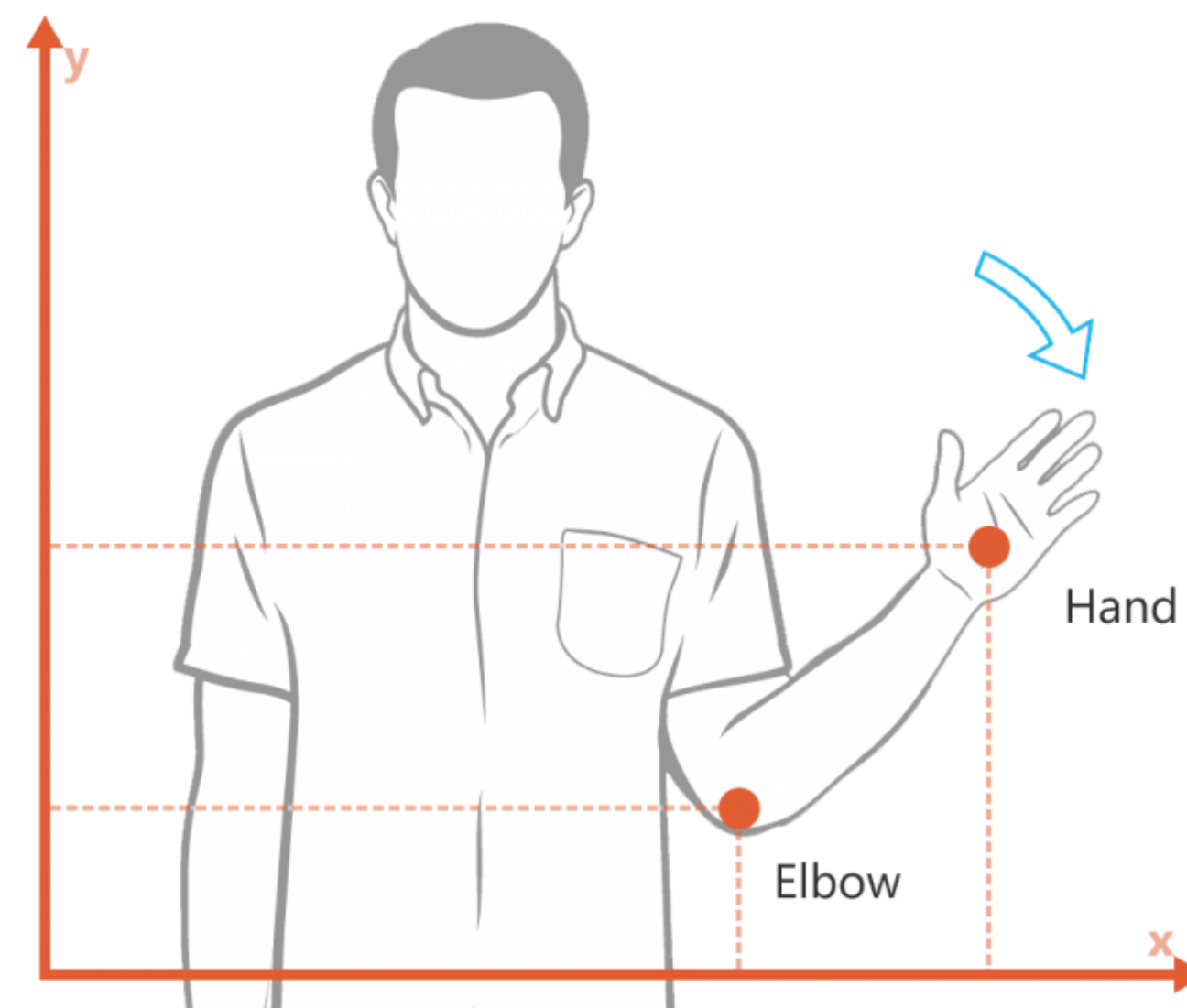
Kinect vs Leap Motion: Kinect has a wider action range and enough accuracy.



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INTERFACE

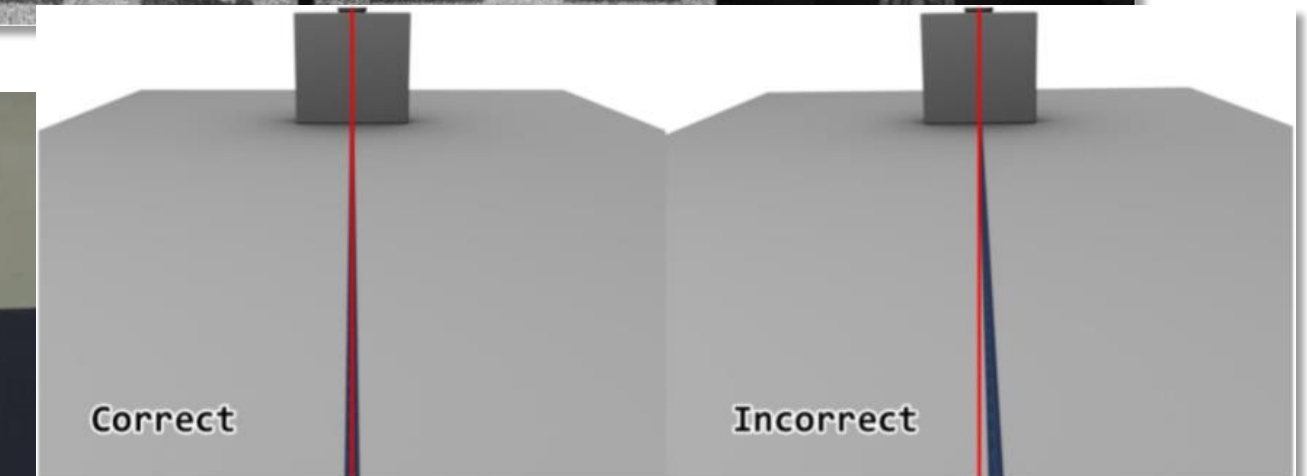
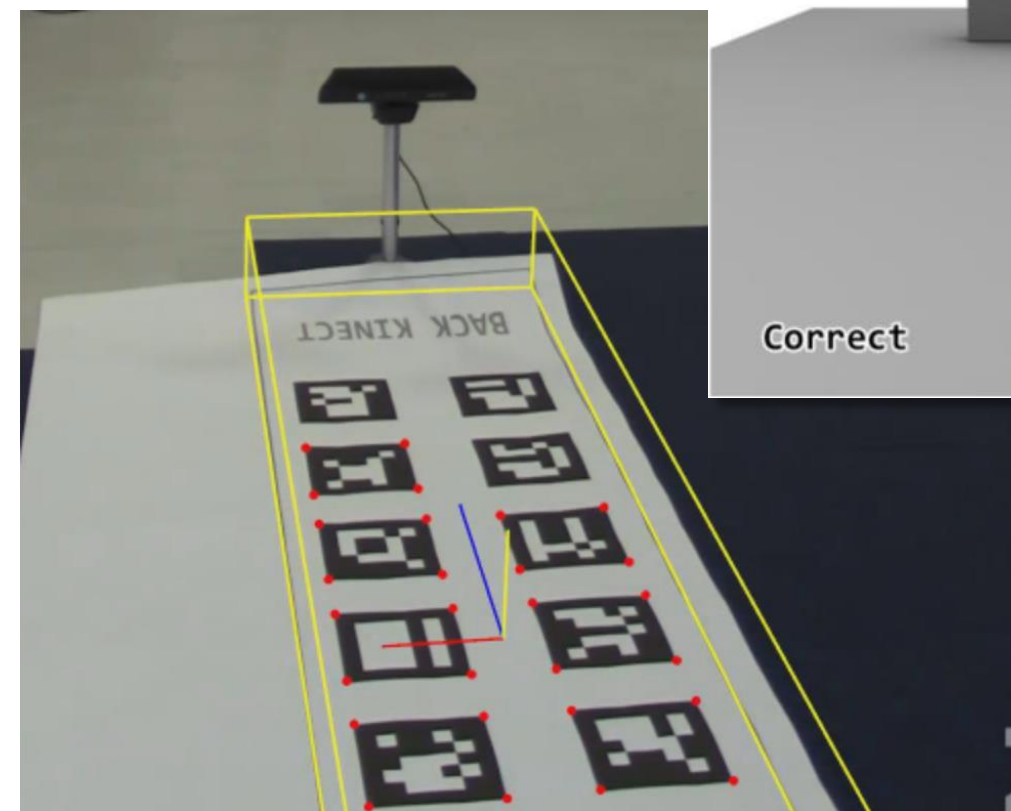
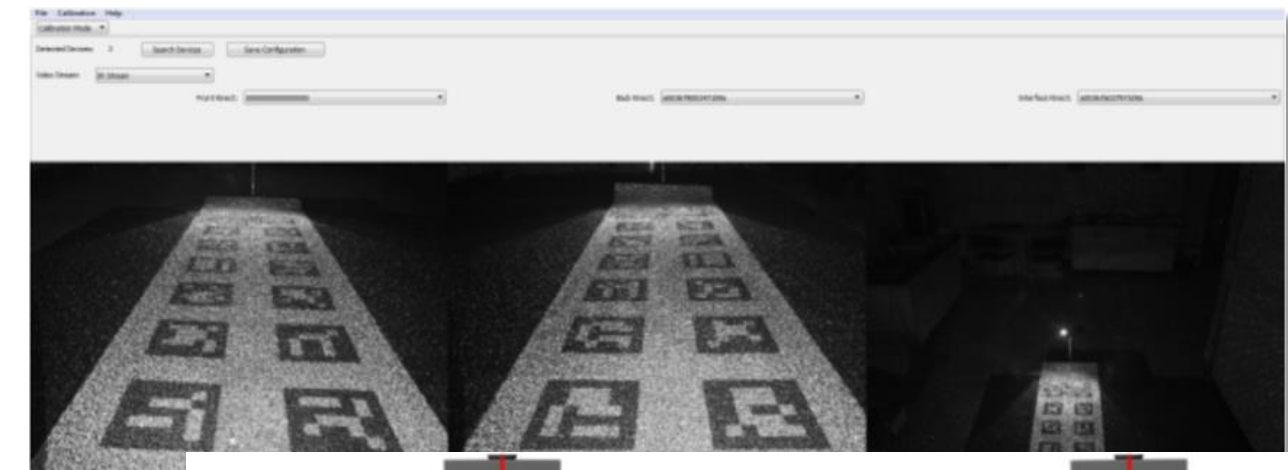
- Selection through position of the hand
- Selection through displacement of the hand
- Selection through angle hand-elbow
- Selection through wheel
- Static-time pulse
- Pushing pulse



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POSE SYSTEM

- © Feet tracking:
Kinect sensors, SDK and ShoeMirror software.
Calibration and detection of the feet.
- © Visualisation of the rendered model.
Wavefront OBJ and OpenGL.
- © Visualisation of photographed models
Developed by CTCR.



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VISUALIZATION OF PHOTOGRAPHED MODELS

- Model defined by several photographs (PhotoShot360[®]).
- Format personalised by CTCR.
- Compression system developed by CTCR.



Algorithm	Complexity for compression	Complexity for decompression
LZW	$N \log_2 N$	N
Huffman	$2N$	N
RLE	N	N
DCT	$N \log_2 N$	$N \log_2 N$
HDT	$N \log_2 N$	$N \log_2 N$
EZW	$N \log_2 N$	$N \log_2 N$

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VISUALIZATION OF PHOTOGRAPHED MODELS

Precision:



Original

99,2%

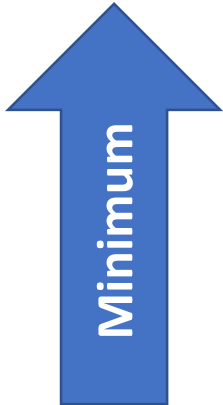
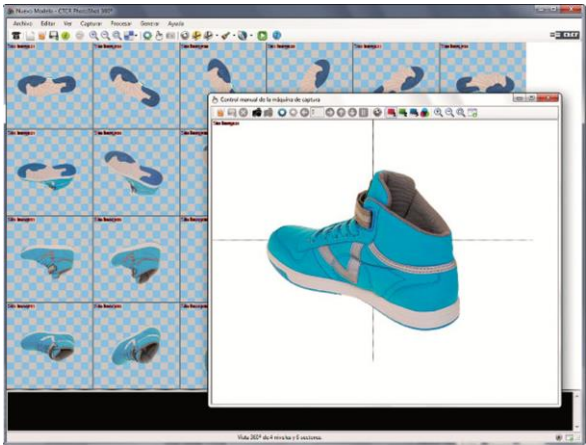


99,5%



99,6%

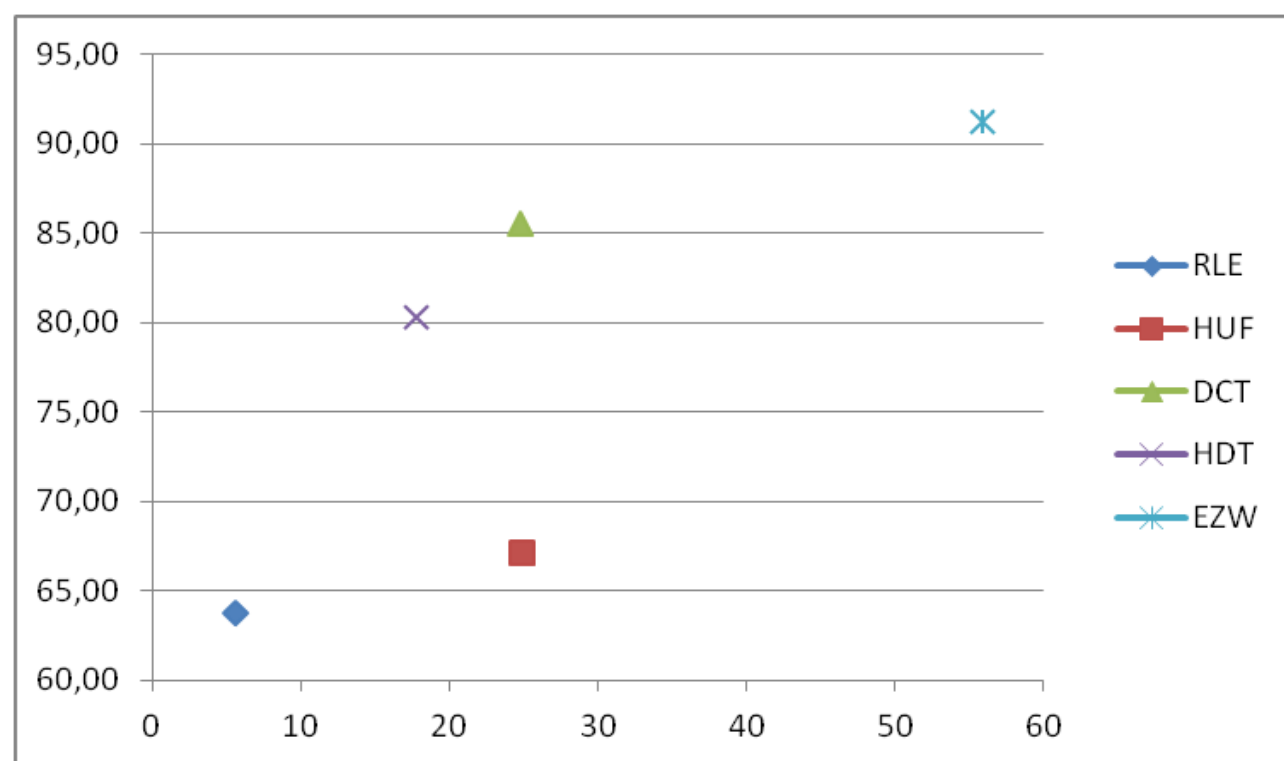
99,7%



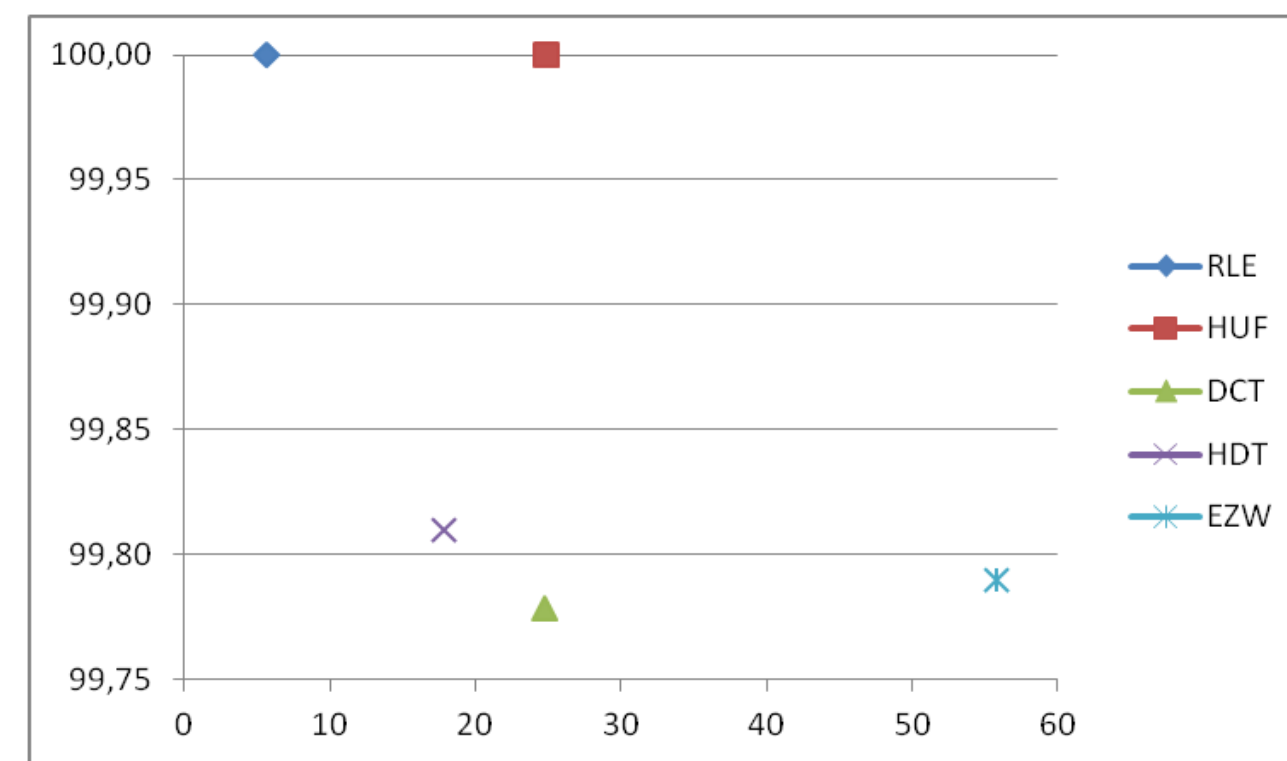
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VISUALIZATION OF PHOTOGRAPHED MODELS

Comparison between compression methods:



Time vs Compression Rate



Time vs Precision

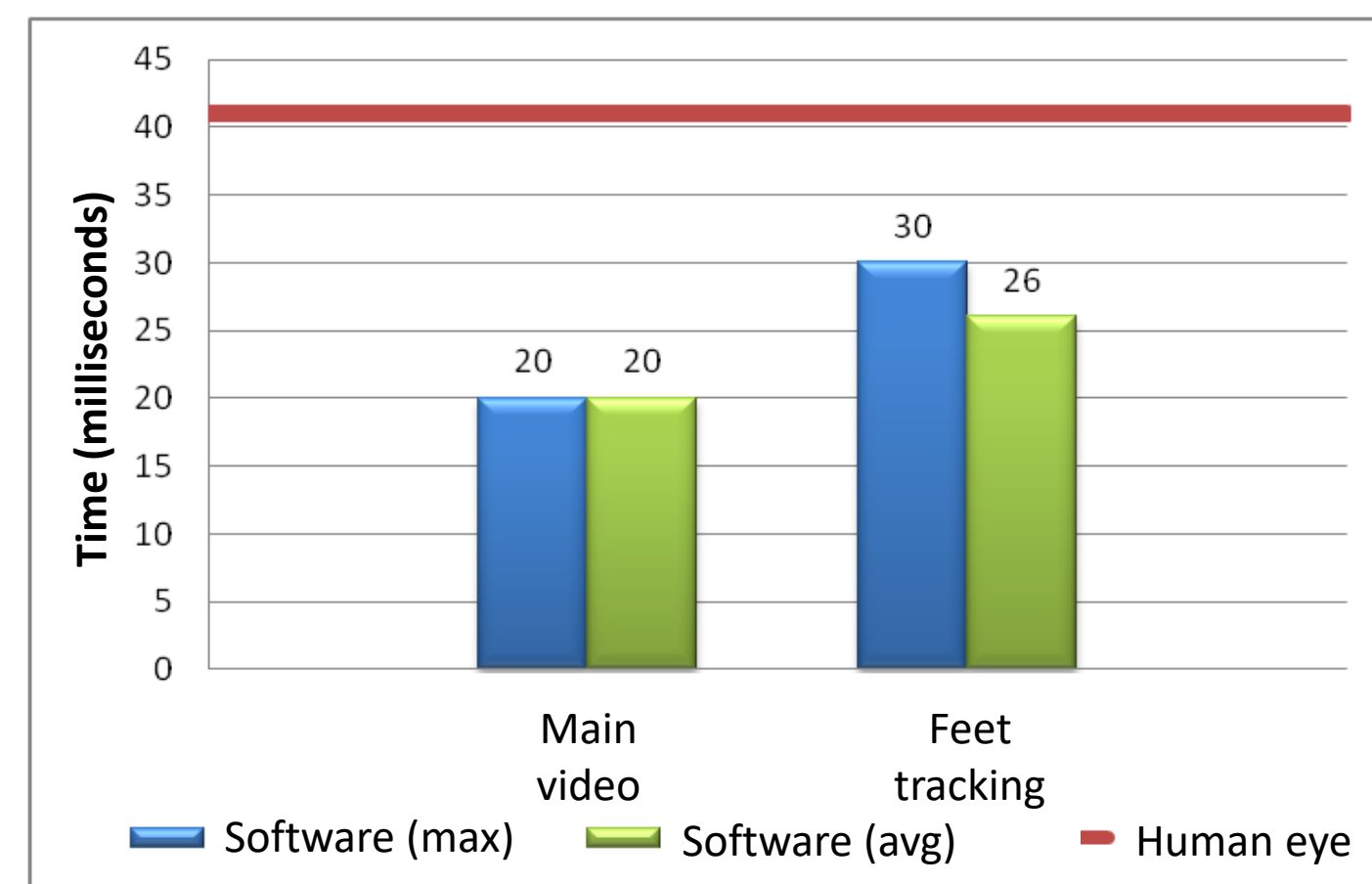
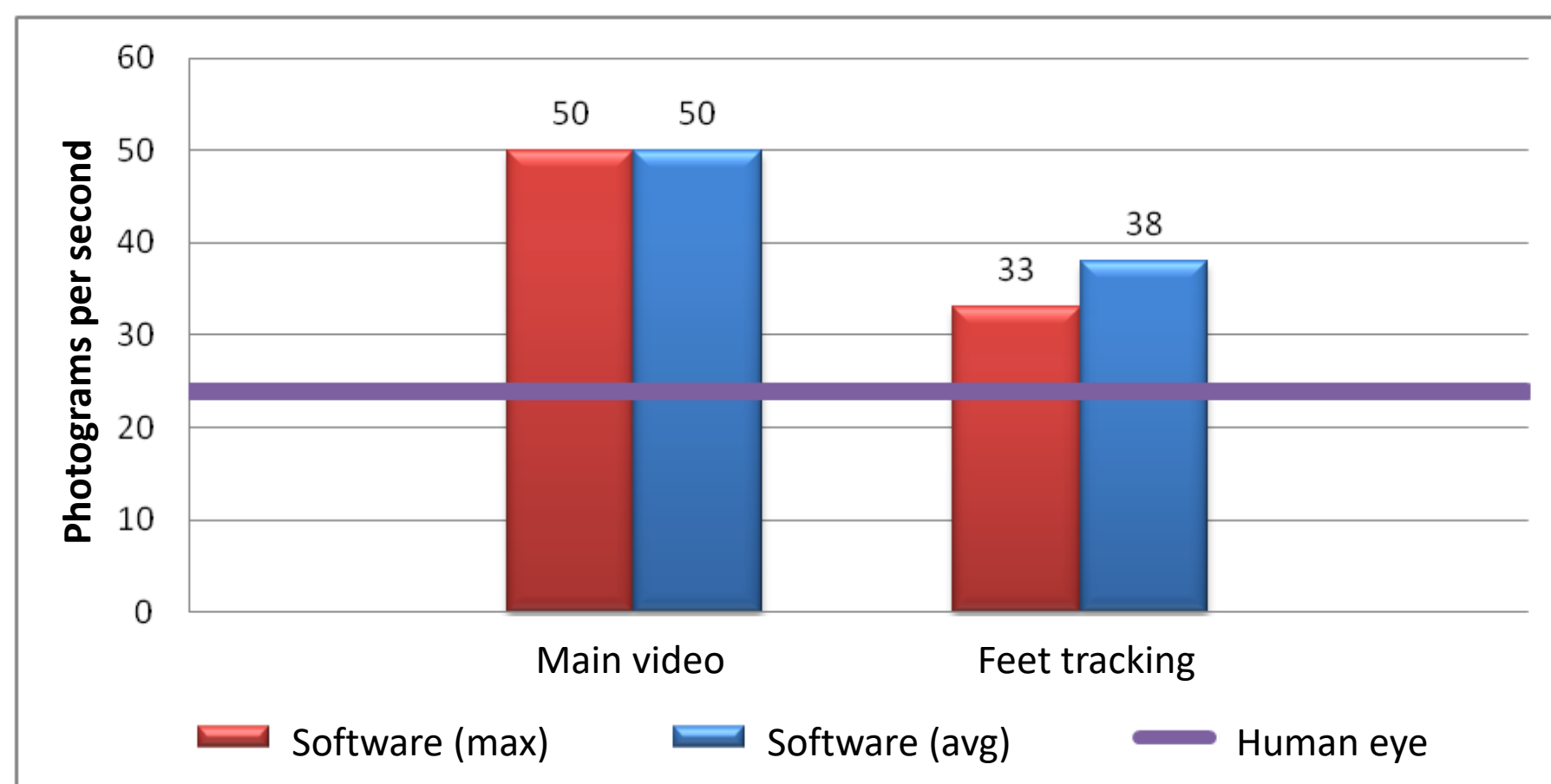
**Solution: combination of HDT and RLE methods and codification through ALCrCb system
(Alfa, Luminance, red Chrominance, blue Chrominance)**

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PERFORMANCE OF THE SYSTEM: PARALLEL RUN

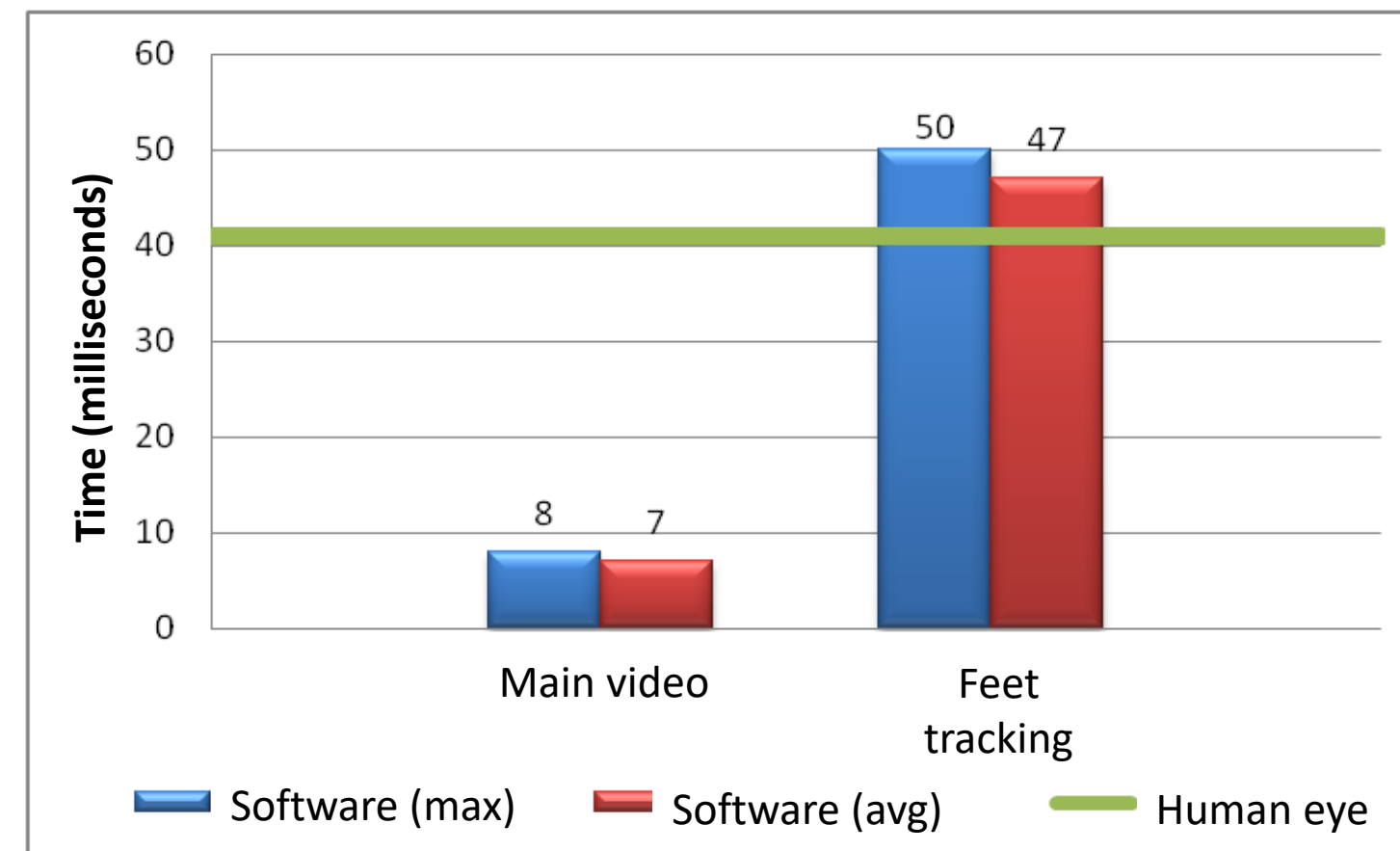
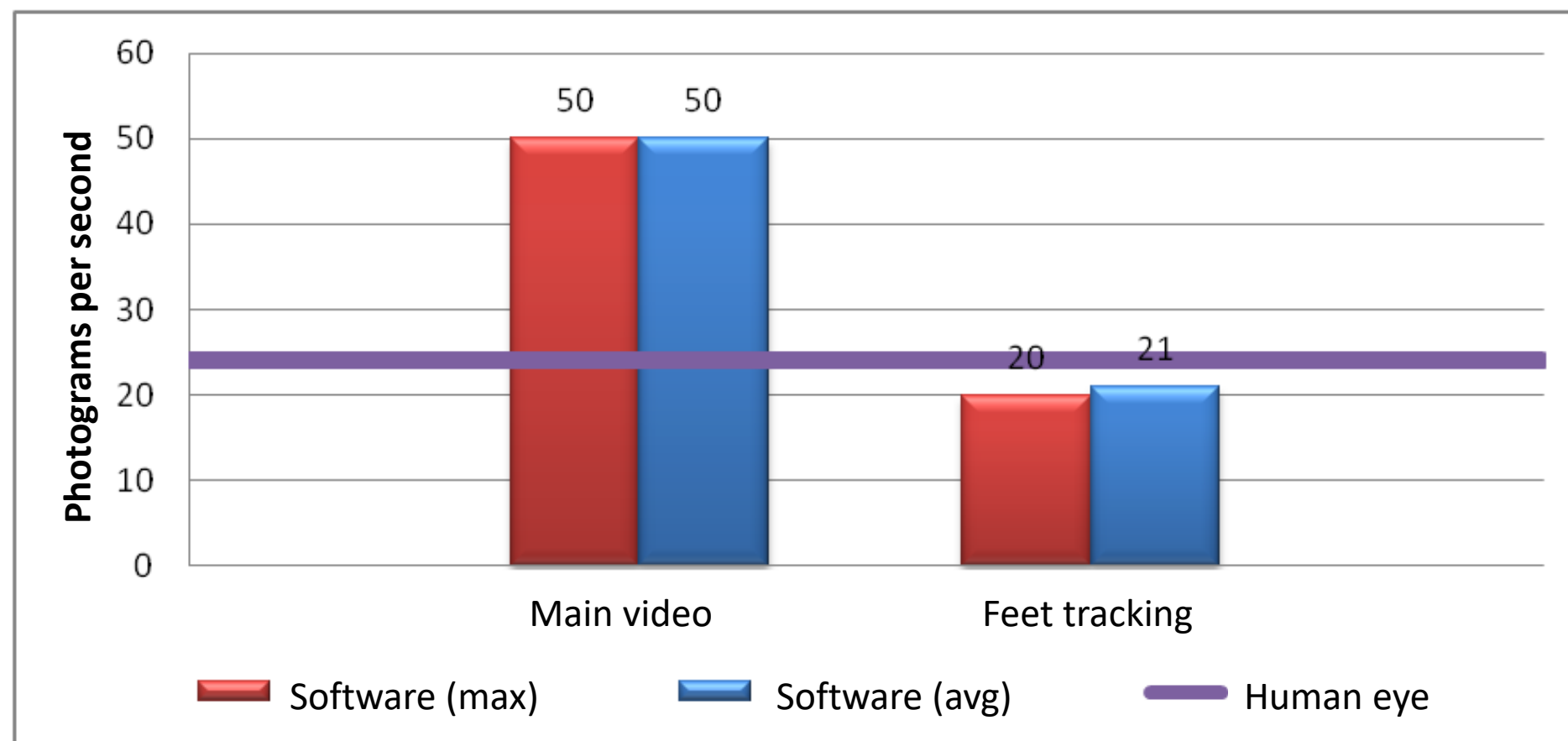


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PERFORMANCE OF THE SYSTEM: SEQUENTIAL RUN



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ADVANTAGES

- The **customers** will improve the shopping experience and will have the service of a virtual personal shopper. They will count on the whole catalogue, not only the shoes that are in the shop.
- The **shop** will increase its sales, because the customers will enjoy at the shop and the service offered will be better.

The **manufacturer** and the **shop** will obtain valuable data from the virtual fitting room: most interesting models, most used sizes, favourite colours...

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Thank you for your attention



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